



MSR 5000
PERFORMANCE
MEETS
PRECISION



made by MAHA
made
in
Germany



MAHA SINGLE ROLLER DYNAMOMETERS

- From the single-axle dynamometer to the high-tech single roller four-wheel performance dynamometer
- Precise measurement technology and reliable, reproducible measurement results
- Sturdy and safe design
- Compatible with previous MSR 500 and LPS 3000 foundations
- For performance measurement, load simulation and driving cycles
- Eddy current brake + electric machine – simulation of real road conditions

01



Electric machine for four-wheel synchronisation:
Tracking acceleration of the non-driven axle
30 kW, 1.5 m/s² up to 200 km/h
30 kW, 1.0 m/s² up to 240 km/h
All drive concepts can be tested

02

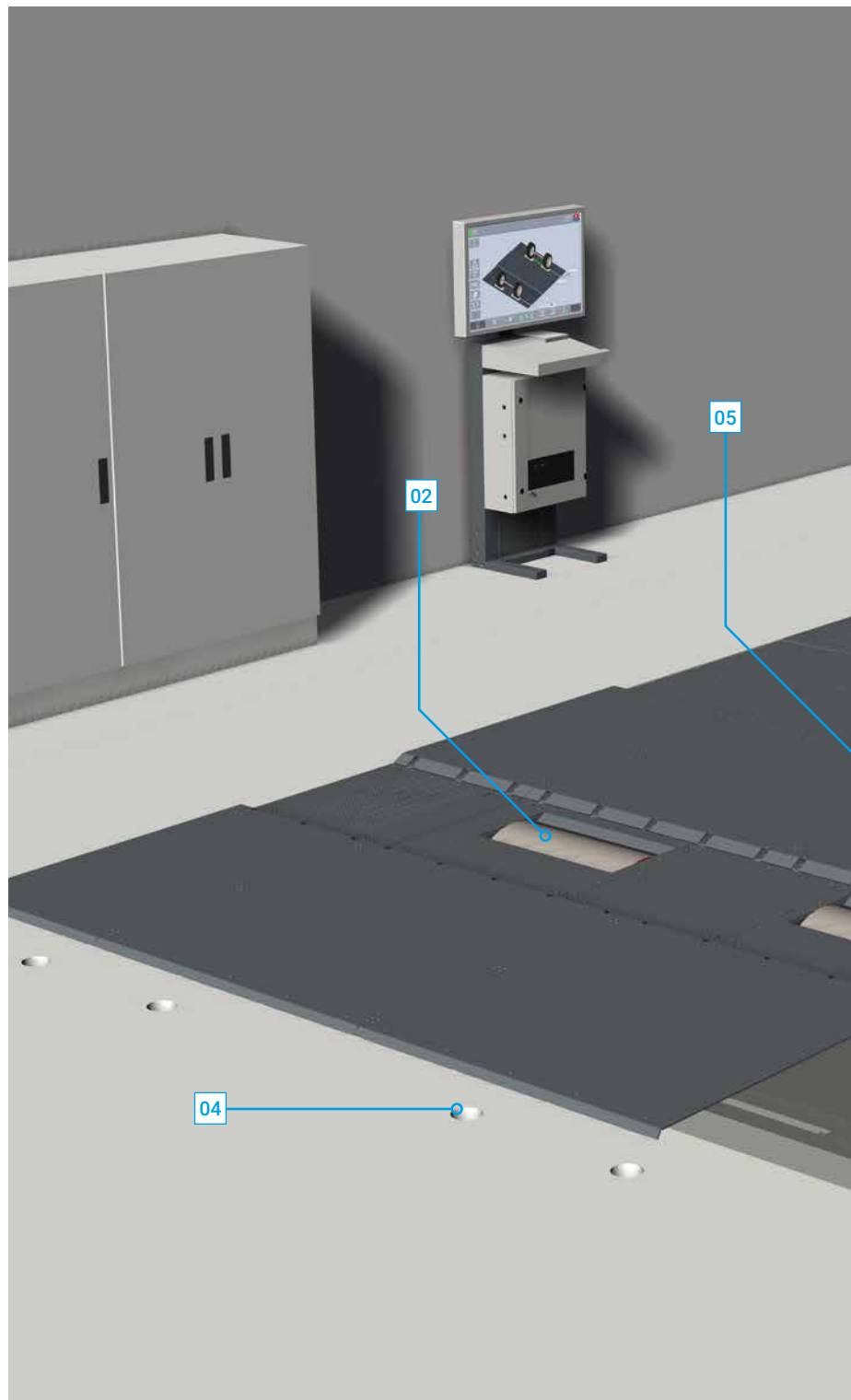


Ni/Cr coating of the rollers for better grip

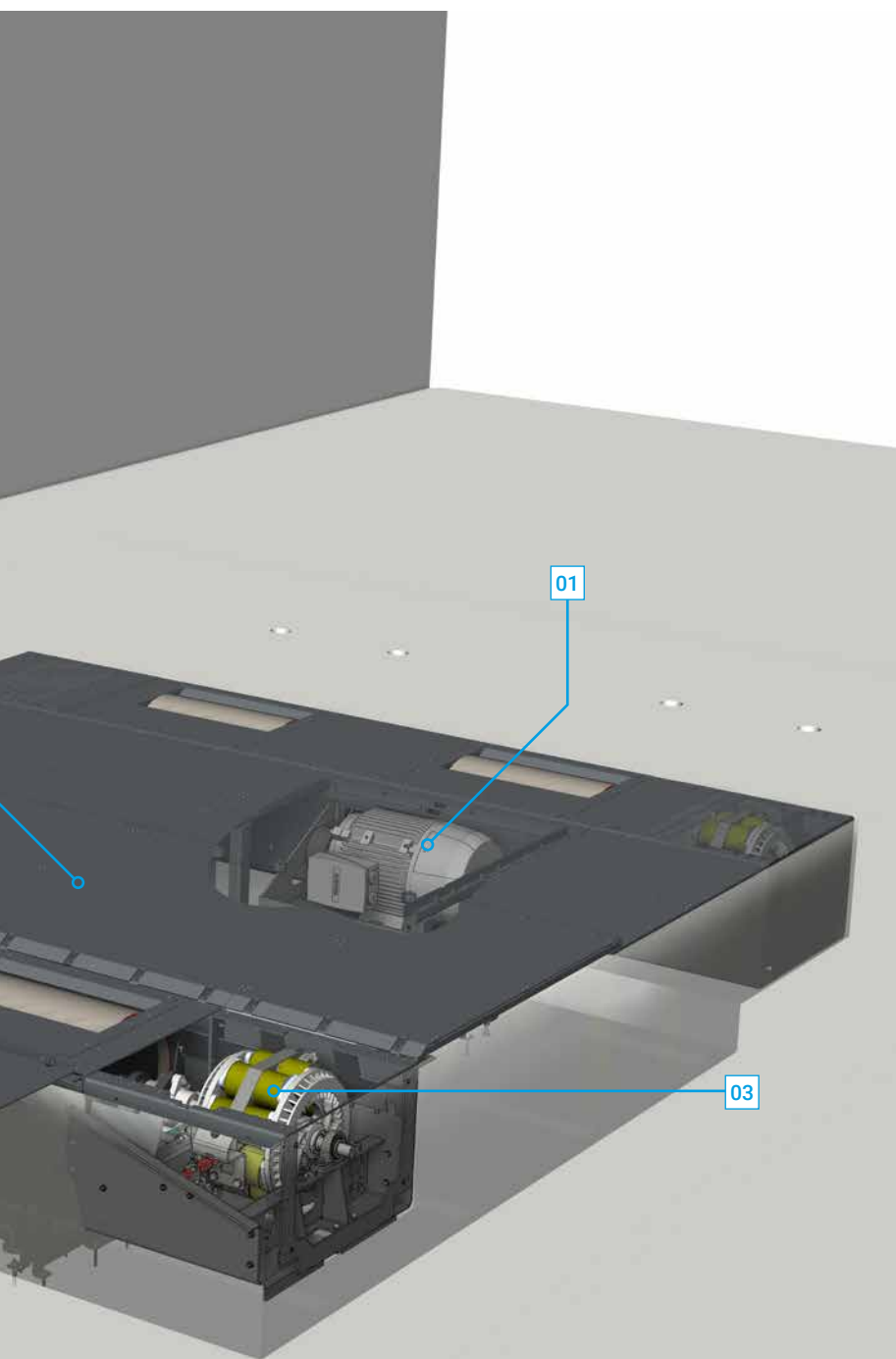
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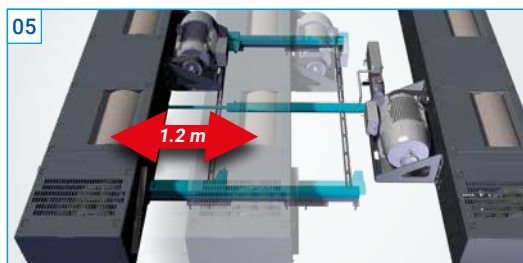
Eddy current brake for performance measurement and load simulation:
7000 N max. tractive force per axle with 1 brake
Max. expansion stage with 4 brakes per dynamometer
Boost function incl. temperature monitoring of the brake especially for performance measurements on electric vehicles



MAHA's MSR single-roller performance and function dynamometer is designed for use in vehicle workshops, motor-sports, universities, schools and testing organisations. This dynamometer makes it easy to perform measurements on vehicles with high engine power or tests with a long test duration. The use of electric machines to drive the rollers in combination with powerful eddy current brakes enables perfect synchronous running of the front and rear axles on the four-wheel MSR. This means that a wide range of vehicles with four-wheel drive systems, but also single-axle driven vehicles, can be tested accurately and effectively. For vehicles driven by a single axle the non-driven axle can be run at the same speed as the drive axle using the electric motor of the dynamometer. Furthermore, the dynamometer is also suited for testing hybrid and electric vehicles thanks to the individual control of the axles.



Vehicle restraint for maximum safety during operation



Hydraulic roller set displacement
2.2 m – 3.4 m stepless adjustable wheelbase.
Thanks to optimised electric machine positioning, it can be installed in all existing dynamometer foundations without any adjustments necessary.



Dynamometer operation from the vehicle via a tablet that complies with the Machinery Directive – ideal for daily operation

THE SOFTWARE

PERFORMANCE MEASUREMENT COMBUSTION ENGINE / ELECTRIC CAR



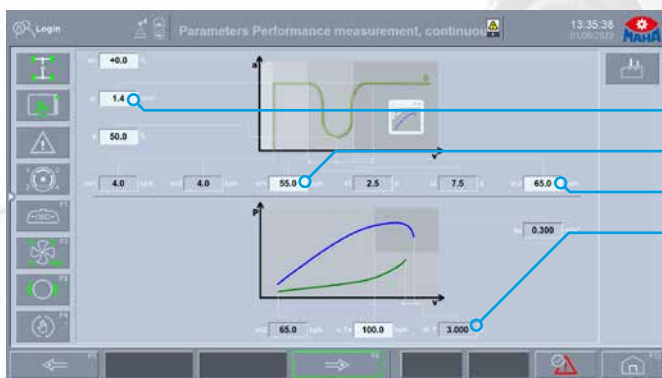
Vehicle data selection: specification of vehicle with electric motor or combustion engine possible

- Drive axle selection
- Tablet connection
- Active warnings (incl. archive)
- Lambda sensor
- OBD port
- Cooling fan
- Parking brake
- "Controlled deceleration" mode of the dynamometer



Automatic mass determination necessary for all vehicle types, as the real value per axle is unknown

- Only possible for electric drive on the roller set
- Extremely accurate and separate mass determination for front and rear axle
- Extremely precise performance measurement possible



Special settings for adaptation of the dynamometer to the individual vehicle

- Acceleration
- Controller start speed
- Start speed of the performance measurement
- Trigger for recording the drag power



User-friendly and clearly presented selection of rotational speed measurement

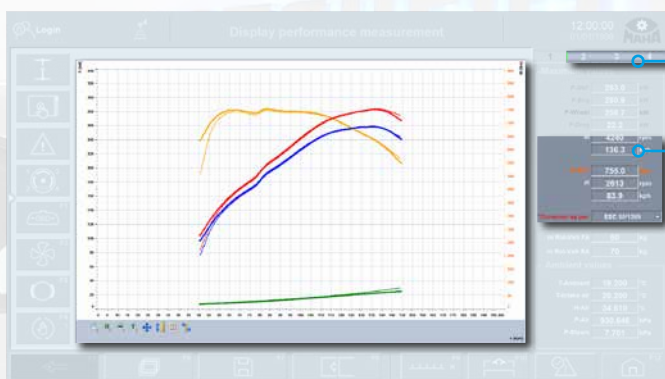
- Possible rotational speed sources:
 - Optical (laser light barrier); 2 inputs for separate detection of wheel rotational speeds
 - OBD
 - Driving test

The maximum engine power of the vehicle is determined in the Performance Measurement operating mode. As the evaluation on a current electric vehicle shows, the MSR also equips you for future electric vehicles. The menu-guided procedure leaves nothing to be desired by the operator, allowing reproducible measurements to be performed with ease.



Full control over all relevant parameters during performance measurement

- Additional values can be freely selected via different display types during performance measurement
- Active drag power measurement
- Display available in each screen for the speed of both axles
- Power distribution of both axles is always in view
- Sidebar for quick access and overview of further dynamometer functions



Easy-to-read result screen

- Best reproducibility with successive measurements. Up to 3 background measurements can be loaded for comparison.
- Additional values (up to 6 channels) can be imported via:
 - OBD
 - Ambient data
 - Analogue inputs
 - Lambda sensor

Mustermann GmbH Musterstraße Musterhausen www.muster.com			
Vehicle type: Volkswagen ID 4 Pro 150 kW Vehicle registration number: MAHA Vehicle ID:			
Drive position: Continuous Transmission mode: Manual Dyno mode: Rear-wheel drive, Axles synchronized Inspector: Armin		Slippage power: 0.0 % Speed offset: 0.0 % Acceleration: 1.5 m/s ²	
Performance data Standard power* P-Standard 206.6 PS / 152.1 kW Engine power P-Engine 206.6 PS / 152.1 kW Wheel power P-Wheel 197.7 PS / 145.4 kW Drag power P-Drag 9.0 PS / 6.6 kW Max. power at 7714.2 rpm / 79.4 kph Torque* M-standard 326.7 Nm Max. torque at 3234.8 rpm / 31.7 kph Max. torque achieved 12166.2 rpm / 127.4 kph * Correction acc. to (No correction)** ** Electric engine / No or mech. supercharger		Ambient data Ambient temperature T-Ambient 28.2 °C Intake air temperature T-Intake air 28.5 °C Relative humidity H-Air 30.9 % Air pressure p-Air 935.1 hPa Steam pressure p-Steam 11.8 hPa Oil temperature T-Oil 28.7 °C	
Rotating mass m rot-Total-FA 318.0 kg m rot-Dyno-FA 280.0 kg m rot-Vehicle-FA 38.0 kg m rot-Total-RA 426.0 kg m rot-Dyno-RA 280.0 kg m rot-Vehicle-RA 146.0 kg			

Mustermann GmbH Musterstraße Musterhausen www.muster.com			
Vehicle type: Porsche GT 4 RS Vehicle registration number: MAHA Vehicle ID:			
Drive position: 5th gear Transmission mode: Manual Dyno mode: Rear-wheel drive Inspector: Michael		Slippage power: 0.0 % Speed offset: 0.0 % Acceleration: 1.5 m/s ²	
Performance data Standard power* P-Standard 499.4 PS / 367.3 kW Engine power P-Engine 465.6 PS / 342.4 kW Wheel power P-Wheel 426.5 PS / 315.9 kW Drag power P-Drag 36.1 PS / 26.6 kW Max. power at 8270.4 rpm / 216.8 kph Torque* M-standard 460.3 Nm Max. torque at 6233.7 rpm / 163.2 kph Max. torque achieved 8950.3 rpm / 235.0 kph * Correction acc. to EEC 80/1269** ** Petrol engine / No or mech. supercharger		Ambient data Ambient temperature T-Ambient 17.2 °C Intake air temperature T-Intake air 20.8 °C Relative humidity H-Air 52.3 % Air pressure p-Air 933.5 hPa Steam pressure p-Steam 6.3 hPa Oil temperature T-Oil 0.0 °C	
Rotating mass m rot-Total-RA 323.0 kg m rot-Dyno-RA 280.0 kg m rot-Vehicle-RA 43.0 kg			

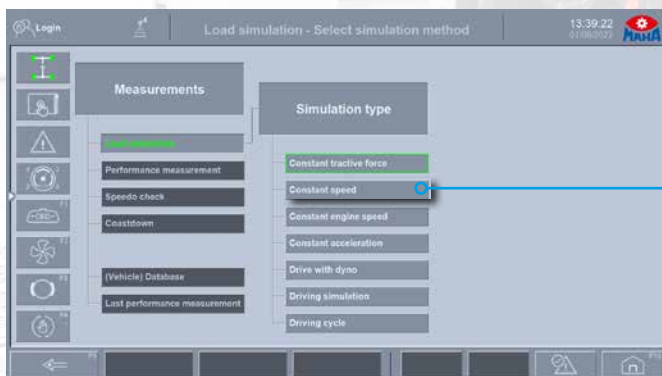
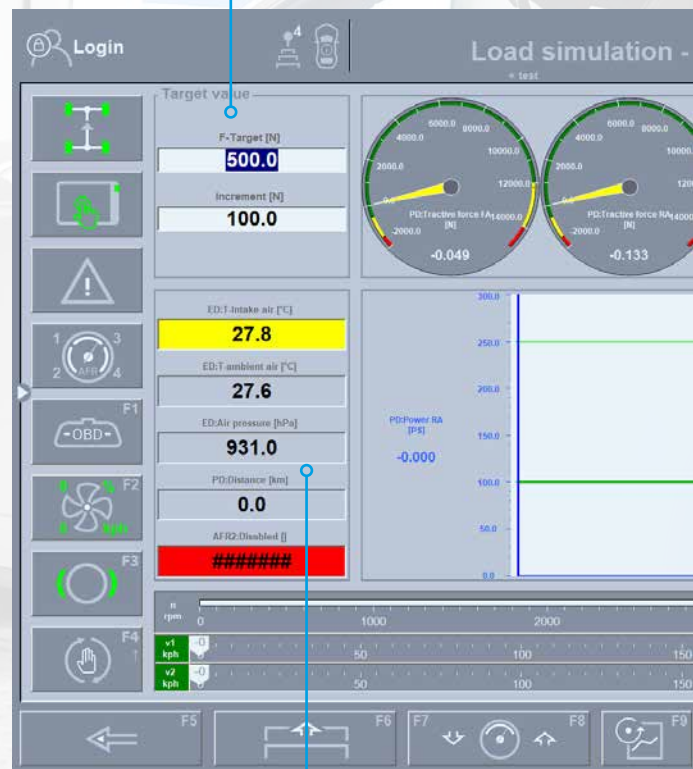
LOAD SIMULATION OPERATING MODE

The Load Simulation operating mode is excellent for tuning work on the vehicle. The load simulation menu allows the user to preselect different load conditions, which can enable targeted engine diagnostics or allow the climbing performance of a vehicle to be determined. Depending on the requirements, various load conditions can be simulated, such as a constant tractive force, constant speed, constant rotational speed or driving simulation.

Oil temperature of the vehicle via temperature sensor

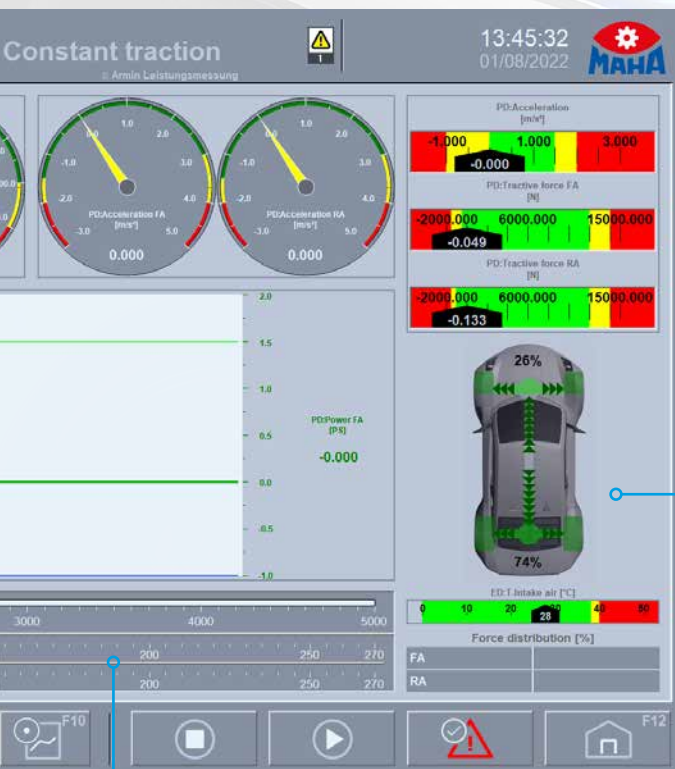


Setting of target values depending on the load simulation type



Monitoring of ambient data:
 - Intake air temperature
 - Relative humidity
 - Ambient temperature

Individually adjustable display of all vehicle and dynamometer relevant values



Power distribution on front/rear axle. Display and monitoring of the eddy current brake engagement or assistance by the electric machine for dynamometer synchronisation

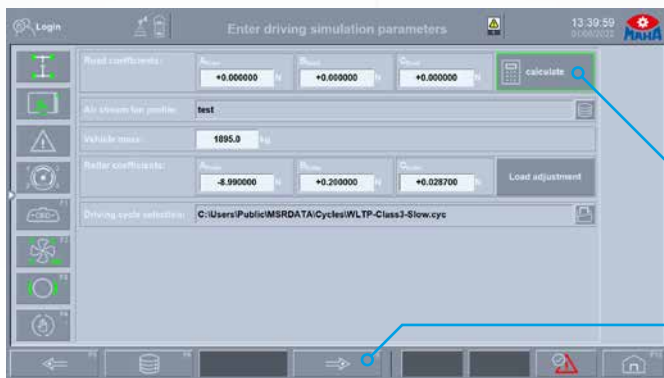
Rotational speed of both axes

LOAD ADJUSTMENT OPERATING MODE

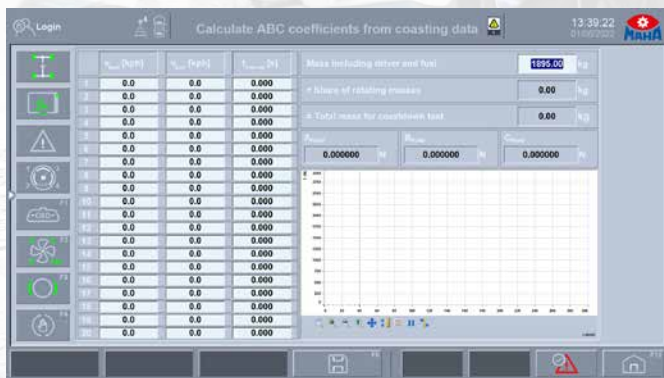
The Load Adjustment operating mode can be used to determine the dynamometer coefficients according to ECE / SA J2264 standards. Depending on the selected method, the vehicle is accelerated to the target speed and the coasting test is initiated. The dynamometer is then braked according to the preset simulation model. This determines the values that make an exact driving simulation "as on the road" possible.

DRIVING CYCLE OPERATING MODE

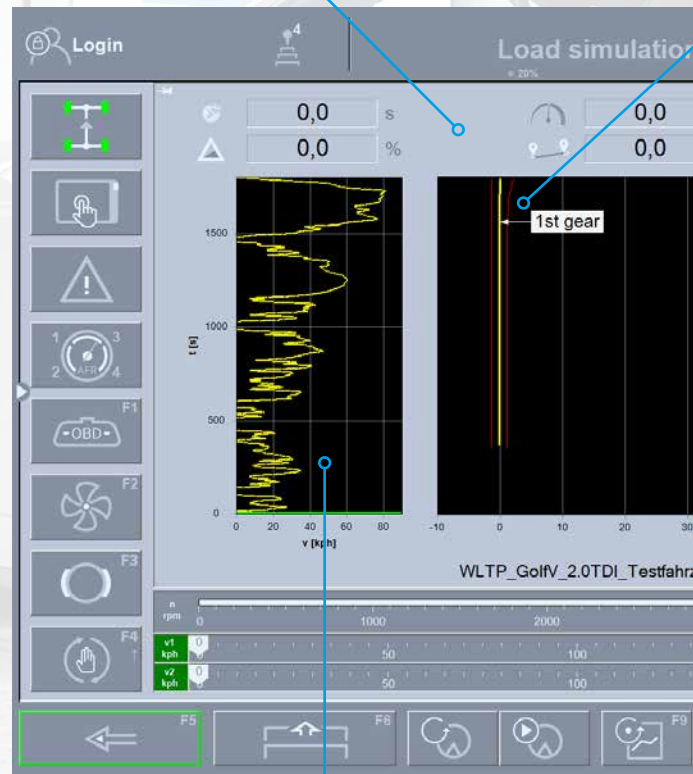
In the Driving Cycle operating mode, it is possible to retrace a speed profile with defined time and speed curves on the dynamometer. Dynamometer coefficients can be determined in the load adjustment. This transfers the vehicle's road coefficients to the dynamometer allowing an exact simulation of a road journey. The exact evaluation of the vehicle in driving mode with a self-selected or standardised driving profile is also possible and can be performed very accurately. Electric machine assisted simulation of the vehicle mass, unique in this segment.



Load adjustment with determination of the dynamometer coefficients. Real values of the vehicle can be used and transferred to the dynamometer



Calculation of the ABC coefficients from the vehicle coasting data on the dynamometer



Cycle time, gradient, current speed and track travelled can be read on the display

Total cycle profile above speed

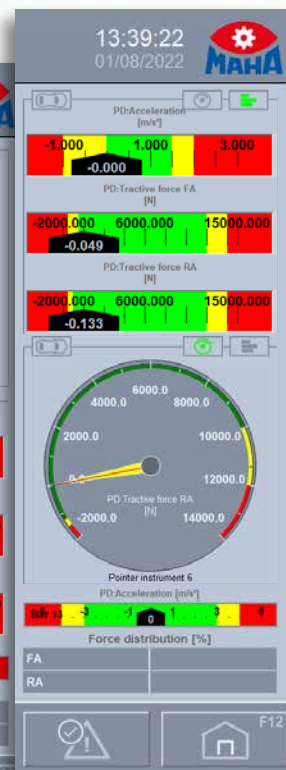
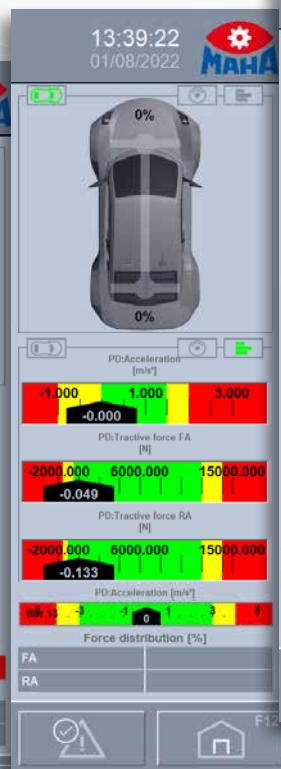
Driving cycle

- User-friendly thanks to menu-guided procedure
- Integrated gear cycles, freely configurable individual cycles.
- Cycle profile can be selected from database
- Driving coefficients for driving simulation can be stored separately in the database for each vehicle
- Road coefficients can be transferred to the dynamometer

Speed tolerance limits
always in view



Driver display with driver
information and gear
shifting instructions



Individual display:
options for monitoring
the dynamometer or
data relevant to the
tested vehicle

INTERFACE BOX

Transfer of additional vehicle values to the dynamometer control system by means of different sensors.

Comes with VESA mount as standard for assembly on wall, stand, support arm, etc.

Analogue input module

Module for current-/voltage-based sensor technology (8 channels)

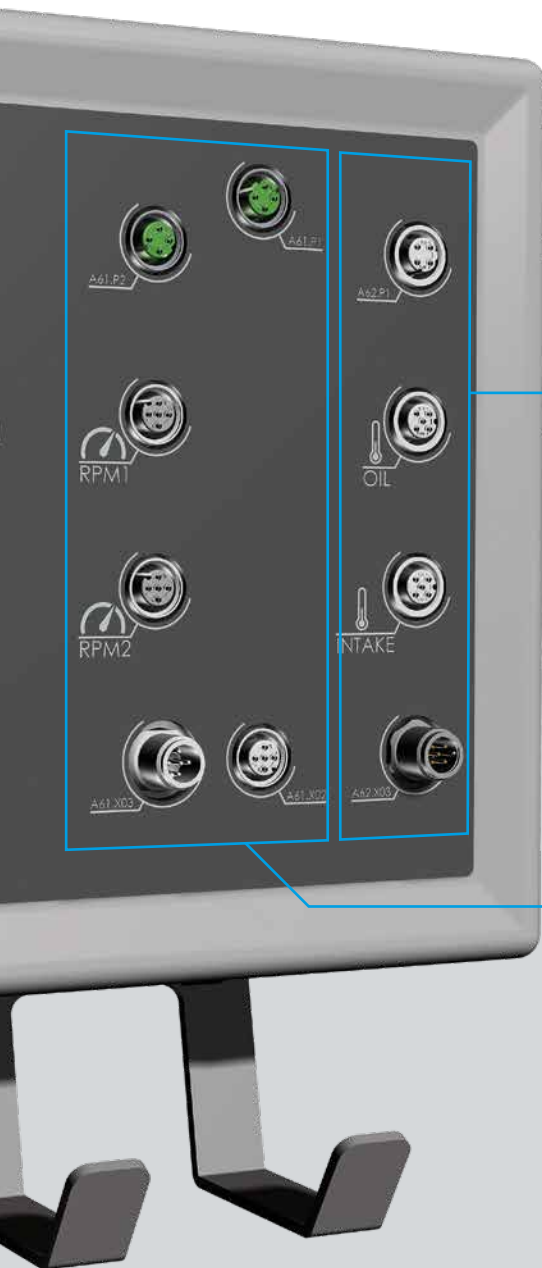


Lambda

- Communication via Wi-Fi
- Exact values, transmitted very quickly
- Recording via load simulation or performance measurement

OBD

- OBD II interface implemented according to standard and WWH OBD GTR
- Free choice of OBD dongle (prerequisite: support of the ELM chip)
- Vehicle-specific PIDs can be queried
- Data about rotational speed, lambda, ignition timing, temperatures, etc. can be provided, recording is vehicle-dependent



Environmental module

Provides data for extrapolations (ambient temperature, humidity, air pressure)

Rotational speed module

Rotational speed input for optical sensors

Laser light signal transmitter:

- Rotational speed measurement on the wheel via laser light barrier, quick to install, easy to use
- Precise determination of the wheel rotational speed for separate recording of the front/rear rotational speeds

DYNAMOMETER VARIANTS

	Eddy current brake	Drive power	Electric machine tractive force	Model
SINGLE AXLE				
	1	30 kW	1500 N	MSR 1500 / 1
	2	30 kW	1500 N	MSR 1500 / 2
FOUR-WHEEL				
	2	30 kW*	3000 N	MSR 3000 / 2
	3	30 kW*	3000 N	MSR 3000 / 3
	4	30 kW*	3000 N	MSR 3000 / 4
	4	37 kW*	3600 N	MSR 5000 / 4

*per axle

BR053501-en 01 - Subject to technical changes without notice. The illustrations include options not part of the standard scope of delivery.